



**TÉCNICO**  
LISBOA



**Thesis Title**

**Candidate Full Name**

Thesis to obtain the Master of Science Degree in

**Aerospace Engineering**

Supervisor(s): Prof. Full Name 1  
Dr. Full Name 2

**Examination Committee**

Chairperson: Prof. Full Name

Supervisor: Prof. Full Name 1 (or 2)

Member of the Committee: Prof. Full Name 3

**Month Year**



Dedicated to someone special...



## **Acknowledgments**

A few words about the university, financial support, research advisor, dissertation readers, faculty or other professors, lab mates, other friends and family...



## Resumo

Inserir o resumo em Português aqui com o máximo de 250 palavras e acompanhado de 4 a 6 palavras-chave...

**Palavras-chave:** palavra-chave1, palavra-chave2,...





## Abstract

Insert your abstract here with a maximum of 250 words, followed by 4 to 6 keywords...

**Keywords:** keyword1, keyword2,...



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# Nomenclature

## Greek symbols

Angle of attack.

Angle of side-slip.

Thermal conductivity coef cient.

Molecular viscosity coef cient.

Density.

## Roman symbols

$C_D$  Coef cient of drag.

$C_L$  Coef cient of lift.

$C_M$  Coef cient of moment.

$p$  Pressure.

$u$  Velocity vector.

$u; v; w$  Velocity Cartesian components.

## Subscripts

1 Free-stream condition.

$i; j; k$  Computational indexes.

$n$  Normal component.

$x; y; z$  Cartesian components.

ref Reference condition.

## Superscripts

\* Adjoint.

T Transpose.



# Chapter 1

## Introduction

Insert your chapter material here...

### 1.1 Motivation

Relevance of the subject...

### 1.2 Topic Overview

Provide an overview of the topic to be studied...

### 1.3 Objectives

Explicitly state the objectives set to be achieved with this thesis...

### 1.4 Thesis Outline

Briefly explain the contents of the different chapters...



# Chapter 2

## Background

Insert your chapter material here...

### 2.1 Theoretical Overview

Some overview of the underlying theory about the topic...

### 2.2 Theoretical Model 1

The research should be supported with a comprehensive list of references. These should appear whenever necessary, in the limit, from the first to the last chapter.

A reference can be cited in any of the following ways:

Citation mode #1 - [1]

Citation mode #2 - Jameson et al. [1]

Citation mode #3 - [1]

Citation mode #4 - Jameson, Pierce, and Martinelli [1]

Citation mode #5 - [1]

Citation mode #6 - Jameson et al. 1

Citation mode #7 - 1

Citation mode #8 - Jameson et al.

Citation mode #9 - 1998

Citation mode #10 - [1998]

Several citations can be made simultaneously as [2, 3].

This is often the default bibliography style adopted (numbers following the citation order), according to the options:

```
nusepackage{natbib} in le Thesis _Preamble.tex ,
```

```
nbibliographystyle {abbrvnat} in le Thesis.tex .
```

Notice however that this style can be changed from numerical citation order to authors' last name with the options:

```
nusepackage[numbers]{natbib} in le Thesis _Preamble.tex ,
```

```
nbibliographystyle {abbrvnatsrnat} in le Thesis.tex .
```

## 2.3 Theoretical Model 2

Other models...

# Chapter 3

## Implementation

Insert your chapter material here...

### 3.1 Numerical Model

Description of the numerical implementation of the models explained in Chapter 2...

### 3.2 Verification and Validation

Basic test cases to compare the implemented model against other numerical tools (verification) and experimental data (validation)...





# Chapter 4

## Results

Insert your chapter material here...

### 4.1 Problem Description

Description of the baseline problem...

### 4.2 Baseline Solution

Analysis of the baseline solution...

### 4.3 Enhanced Solution

Quest for the optimal solution...

#### 4.3.1 Figures

Insert your section material and possibly a few figures...

Make sure all figures presented are referenced in the text!

Images

Figure 4.1: Caption for figure.

(a) Airbus A320

(b) Bombardier CRJ200

Figure 4.2: Some aircrafts.

Make reference to Figures 4.1 and 4.2.

By default, the supported file types are .png,.pdf,.jpg,.mps,.jpeg,.PNG,.PDF,.JPG,.JPEG.

See [http://mactex-wiki.tug.org/wiki/index.php/Graphics\\_inclusion](http://mactex-wiki.tug.org/wiki/index.php/Graphics_inclusion) for adding support to other extensions.

## Drawings

Insert your subsection material and for instance a few drawings...

The schematic illustrated in Fig. 4.3 can represent some sort of algorithm.

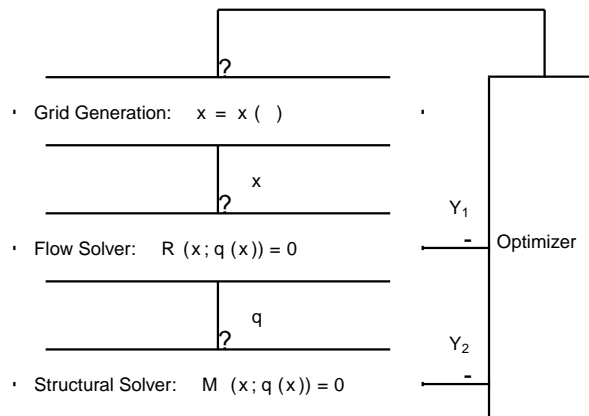


Figure 4.3: Schematic of some algorithm.

## 4.3.2 Equations

Equations can be inserted in different ways.

The simplest way is in a separate line like this

$$\frac{dq_{jk}}{dt} + R_{ijk}(q) = 0 : \quad (4.1)$$

If the equation is to be embedded in the text. One can do it like this  $\rho \frac{\partial \mathbf{u}}{\partial t} = \mathbf{0}$ .

It may also be split in different lines like this

$$\begin{aligned} &\text{Minimize} && Y(\mathbf{u}; \mathbf{q}) \\ &\text{w.r.t:} && \mathbf{u}; \\ &\text{subject to} && \mathbf{R}(\mathbf{u}; \mathbf{q}) = \mathbf{0} \\ &&& \mathbf{C}(\mathbf{u}; \mathbf{q}) = \mathbf{0} : \end{aligned} \tag{4.2}$$

It is also possible to use subequations. Equations 4.3a, 4.3b and 4.3c form the Navier–Stokes equations 4.3.

$$\frac{\partial}{\partial t} \mathbf{u}_i + \frac{\partial}{\partial x_j} (\mathbf{u}_j) = 0 ; \tag{4.3a}$$

$$\frac{\partial}{\partial t} (\mathbf{u}_i) + \frac{\partial}{\partial x_j} (\mathbf{u}_i \mathbf{u}_j + p_{ij} - \tau_{ij}) = 0 ; \quad i = 1; 2; 3; \tag{4.3b}$$

$$\frac{\partial}{\partial t} (\mathbf{E}) + \frac{\partial}{\partial x_j} (\mathbf{E} \mathbf{u}_j + p \mathbf{u}_j - \mathbf{u}_i \tau_{ij} + \mathbf{q}) = 0 : \tag{4.3c}$$

### 4.3.3 Tables

Insert your subsection material and for instance a few tables...

Make sure all tables presented are referenced in the text!

Follow some guidelines when making tables:

Avoid vertical lines

Avoid “boxing up” cells, usually 3 horizontal lines are enough: above, below, and after heading

Avoid double horizontal lines

Add enough space between rows

Model	$C_L$	$C_D$	$C_{My}$
Euler	0.083	0.021	-0.110
Navier–Stokes	0.078	0.023	-0.101

Table 4.1: Table caption.

Make reference to Table 4.1.

Tables 4.2 and 4.3 are examples of tables with merging columns:

An example with merging rows can be seen in Tab.4.4.

If the table has too many columns, it can be scaled to fit the text width, as in Tab.4.5.

	Virtual memory [MB]	
	Euler	Navier–Stokes
Wing only	1,000	2,000
Aircraft	5,000	10,000
(ratio)	5:0	5:0

Table 4.2: Memory usage comparison (in MB).

	w = 2			w = 4		
	t = 0	t = 1	t = 2	t = 0	t = 1	t = 2
dir = 1						
c	0.07	0.16	0.29	0.36	0.71	3.18
c	-0.86	50.04	5.93	-9.07	29.09	46.21
c	14.27	-50.96	-14.27	12.22	-63.54	-381.09
dir = 0						
c	0.03	1.24	0.21	0.35	-0.27	2.14
c	-17.90	-37.11	8.85	-30.73	-9.59	-3.00
c	105.55	23.11	-94.73	100.24	41.27	-25.73

Table 4.3: Another table caption.

ABC	header			
	1.1	2.2	3.3	4.4
IJK	group		0.5	0.6
			0.7	1.2

Table 4.4: Yet another table caption.

Variable	a	b	c	d	e	f	g	h	i	j
Test 1	10,000	20,000	30,000	40,000	50,000	60,000	70,000	80,000	90,000	100,000
Test 2	20,000	40,000	60,000	80,000	100,000	120,000	140,000	160,000	180,000	200,000

Table 4.5: Very wide table.

#### 4.3.4 Mixing

If necessary, a figure and a table can be put side-by-side as in Fig.4.4

Legend		
A	B	C
0	0	0
0	1	0
1	0	0
1	1	1

Figure 4.4: Figure and table side-by-side.



# Chapter 5

## Conclusions

Insert your chapter material here...

### 5.1 Achievements

The major achievements of the present work...

### 5.2 Future Work

A few ideas for future work...





# Bibliography

- [1] A. Jameson, N. A. Pierce, and L. Martinelli. Optimum aerodynamic design using the Navier–Stokes equations. In *Theoretical and Computational Fluid Dynamics*, volume 10, pages 213–237. Springer-Verlag GmbH, Jan. 1998.
- [2] J. Nocedal and S. J. Wright. *Numerical optimization*. Springer, 2<sup>nd</sup> edition, 2006. ISBN:978-0387303031.
- [3] A. C. Marta, C. A. Mader, J. R. R. A. Martins, E. van der Weide, and J. J. Alonso. A methodology for the development of discrete adjoint solvers using automatic differentiation tools. *International Journal of Computational Fluid Dynamics*, 99(9–10):307–327, Oct. 2007. doi:10.1080/10618560701678647.



# Appendix A

## Vector calculus

In case an appendix is deemed necessary, the document cannot exceed a total of 100 pages...

Some definitions and vector identities are listed in the section below.

### A.1 Vector identities

$$\mathbf{r} \cdot (\mathbf{r} \times \mathbf{u}) = 0 \quad (\text{A.1})$$

$$\mathbf{r} \cdot (\mathbf{r} \times \mathbf{u}) = 0 \quad (\text{A.2})$$



## **Appendix B**

# **Technical Datasheets**

It is possible to add PDF files to the document, such as technical sheets of some equipment used in the work.

### **B.1 Some Datasheet**

### BENEFITS

#### Maximum Light Capture

SunPower's all-back contact cell design moves gridlines to the back of the cell, leaving the entire front surface exposed to sunlight, enabling up to 10% more sunlight capture than conventional cells.

#### Superior Temperature Performance

Due to lower temperature coefficients and lower normal cell operating temperatures, our cells generate more energy at higher temperatures compared to standard c-Si solar cells.

#### No Light-Induced Degradation

SunPower n-type solar cells don't lose 3% of their initial power once exposed to sunlight as they are not subject to light-induced degradation like conventional p-type c-Si cells.

#### Broad Spectral Response

SunPower cells capture more light from the blue and infrared parts of the spectrum, enabling higher performance in overcast and low-light conditions.

#### Broad Range Of Application

SunPower cells provide reliable performance in a broad range of applications for years to come.

The SunPower™ C60 solar cell with proprietary Maxeon™ cell technology delivers today's highest efficiency and performance.

The anti-reflective coating and the reduced voltage-temperature coefficients provide outstanding energy delivery per peak power watt. Our innovative all-back contact design moves gridlines to the back of the cell, which not only generates more power, but also presents a more attractive cell design compared to conventional cells.

SunPower's High Efficiency Advantage



C60 SOLAR CELL

### Electrical Characteristics of Typical Cell at Standard Test Conditions (STC)

STC: 1000W/m<sup>2</sup>, AM 1.5g and cell temp 25°C

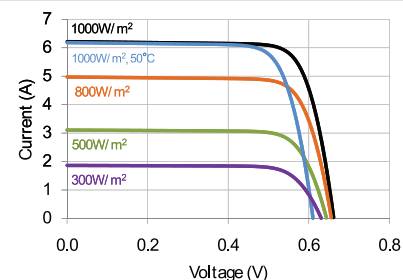
Bin	P <sub>mp</sub> (Wp)	Eff. (%)	V <sub>mp</sub> (V)	I <sub>mp</sub> (A)	V <sub>oc</sub> (V)	I <sub>sc</sub> (A)
G	3.34	21.8	0.574	5.83	0.682	6.24
H	3.38	22.1	0.577	5.87	0.684	6.26
I	3.40	22.3	0.581	5.90	0.686	6.27
J	3.42	22.5	0.582	5.93	0.687	6.28

All Electrical Characteristics parameters are nominal  
Unlaminated Cell Temperature Coefficients  
Voltage: -1.8 mV / °C Power: -0.32% / °C

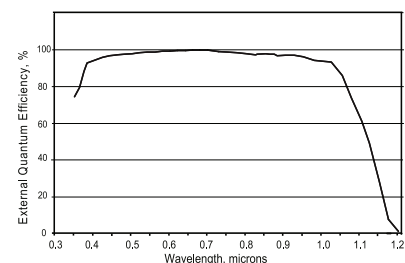
### Positive Electrical Ground

Modules and systems produced using these cells must be configured as "positive ground systems".

### TYPICAL I-V CURVE



### SPECTRAL RESPONSE



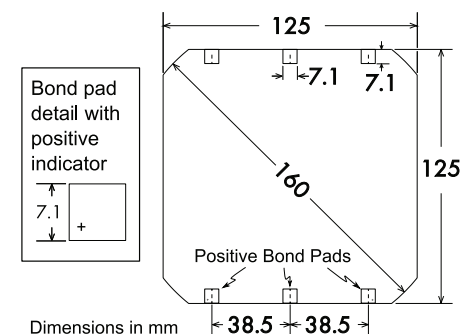
### About SunPower

SunPower designs, manufactures, and delivers high-performance solar electric technology worldwide. Our high-efficiency solar cells generate up to 50 percent more power than conventional solar cells. Our high-performance solar panels, roof tiles, and trackers deliver significantly more energy than competing systems.

### Physical Characteristics

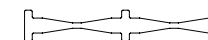
Construction:	All back contact
Dimensions:	125mm x 125mm (nominal)
Thickness:	165µm ± 40µm
Diameter:	160mm (nominal)

### Cell and Bond Pad Dimensions



Bond pad area dimensions are 7.1mm x 7.1mm  
Positive pole bond pad side has "+" indicator on leftmost and rightmost bond pads.

### Interconnect Tab and Process Recommendations



Tin plated copper interconnect. Compatible with lead free process.

### Packaging

Cells are packed in boxes of 1,200 each; grouped in shrink-wrapped stacks of 150 with interleaving. Twelve boxes are packed in a water-resistant "Master Carton" containing 14,400 cells suitable for air transport.

Interconnect tabs are packaged in boxes of 1,200 each.